

From Photo to Fabrication (Photo2Fab)

A Design-to-Fabrication Workflow using Irregular Tree Parts, Machine Learning, and Mixed Reality

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Abstract. As concerns about climate change, sustainability, and resource circularity grow, there is a need to consider the role of waste materials. In this project, we explore the development of a computational design workflow for design and fabrication with non-standardized tree parts of varied shapes and sizes. We describe and compare three machine learning workflows: (1) Generative Adversarial Networks (GANs), (2) Denoising Diffusion Probabilistic Models (DDPM), and (3) Line Segment Detection (LSD) models for feature detection by testing their efficiency and the quality of their results for converting photos of irregular tree parts into usable digital geometry. How can we leverage tree waste, machine learning, and mixed reality to create novel design-to-fabrication workflows in architecture and construction? We then use the best performing workflow to build a digital materials library, digitally model and design with the resulting geometry, and use mixed reality tools and software to build structures. Our results show that DDPMs outperform GANs in detecting and generalizing skeletons of real tree branches from photos. While our dataset of Y-branches were predominantly planar in the Z-axis (depth), our project demonstrates that Photo2Fab is a bottom-up, ecologically responsive approach to material reuse in design, architecture, and construction.

Keywords. Sustainability, Tree Material, Machine Learning (ML), Computer Vision, Mixed Reality (MR), Photo2Fab, DDPM, LSD

1. Introduction

As concerns about climate change, sustainability, and resource circularity grow in the architecture and construction industries, there is a need to consider the role of waste materials. Design and construction with irregular materials of unpredictable shapes and sizes present a challenge as construction typically involves the processing and use of

standardized materials with known dimensions and properties (Zboinska & Göbel, 2025). In this project, we explore the development of a novel computational design workflow for design and fabrication with non-standardized tree parts. Irregularly shaped tree parts and offcuts are often discarded during landscaping and construction. Additionally, increasingly extreme and unexpected weather events have resulted in the breaking of entire trees, branches, and limbs. Emerging computational tools and methods, such as computer vision and extended reality (XR), offer opportunities for new methodologies and a rethinking of architecture's relationships with nature and the built environment. This research project addresses these challenges by using these tools to create a novel design-to-fabrication pipeline we call, Photo2Fab. Our project utilizes computer vision to convert photos of irregular tree parts into usable digital geometry for design. It also employs mixed reality (MR) to assemble and fabricate structures with the tree parts. By developing a computational design-to-production pipeline, the project demonstrates a bottom-up, ecologically responsive approach to material reuse in architecture and construction.

Three objectives of this study are to: (1) reduce tree waste and upcycle non-standard parts to minimize environmental impact; (2) convert photos of geometrically irregular tree parts into design and fabrication-ready digital models; (3) develop a novel photo-to-fabrication workflow to design and build with tree parts. This paper is organized as follows: Background, situates our project within existing scholarship on sustainability and ecological fabrication, digital inventory, and XR in design and fabrication. In Methods, we describe three methods for converting tree geometry into digital geometry, and our digital modeling, design, and fabrication processes. Results, show outputs from the machine learning models, and our culminating structures, while Discussion and Conclusion evaluate the results, consider implications of the work, and outline possible future directions.

2. Background

2.1. SUSTAINABILITY AND ECOLOGICAL FABRICATION PRACTICES

Sustainability promotes resource efficiency, use of renewable materials, and low-impact construction methods. A circular economy advances sustainability in architecture by replacing the traditional start-end linearity with closed-loop systems, where materials are reused, repaired, or recycled (Kibert et al., 2000). Ecological fabrication integrates natural systems, material behavior, and computational design to create fabrication processes that align with ecological dynamics (Guy and Farmer 2001). Existing scholarship combining natural systems and computational design, includes the development of digital and robotic fabrication workflows for non-standardized tree parts (Haghnazar et al., 2024; Wei, 2023); 3D printing with biomaterials (Bell et al., 2025), wood (Dayyem Khan, 2023), and mycelium composites (Dessi-Olive, 2023).

2.2. IRREGULAR MATERIALS AND DIGITAL INVENTORY

Work in documenting and inventorying tree parts includes 3D scanning (Amtsberg et al., 2020); digital modeling (Allner et al., 2020); extracting scanned mesh centerlines

(Cousin et al., 2023); and photogrammetry with smartphones (Chai et al., 2024). These methods are sometimes expensive and require substantial computational power for processing. While replacing 3D scanning with computer vision algorithms or deep learning models presents opportunities, it also presents challenges like capturing the complex geometries of branches, noise and occlusion, and the uncontrolled nature of environments (Kim & Kantor, 2023; Y. Yang et al., 2024). Current research in machine learning methods for detecting irregular tree branches includes Pix2Pix GAN models (Chen et al., 2021; Tong et al., 2022); lightweight convolutional neural network (CNN) models (Wan et al., 2023); central skeleton extraction with cross sections (C. H. Yang et al., 2020); and CNN for probability prediction (Silva et al., 2022).

2.3. EXTENDED REALITY IN DESIGN, FABRICATION & ASSEMBLY

Augmented Reality (AR) and Mixed Reality (MR) are increasingly explored as these technologies become more ubiquitous, affordable, and mobile. Digital software environments and plugins often include Rhino 3D and Grasshopper 3D (digital modeling software by Robert McNeel & Associates), Microsoft HoloLens headsets, and the AR plugin for Rhino 3D, Fologram. Current work includes using AR to manually assemble complex structures from standardized dimensional lumber (Hanke et al., 2023), dowels (Mostafavi et al., n.d.), and friction-fit planes (Atanasova et al., 2023). Manual XR fabrication studies include the fabrication of low-cost, reusable molds (Azambuja Varela et al., 2022), fabrication and assembly of a steam-bent timber structure (Jahn, 2019), and a curved art installation made from bamboo splits (Goepel & Crolla, 2020). Work in manual fabrication and assembly with AR/MR and irregular tree parts includes a tree-log structure (Lok, 2021), and a gridshell structure (Cousin et al., 2023).

3. Methods

3.1. COMPUTER VISION MODELS TO CAPTURE TREE GEOMETRY

3.1.1. *Line Segment Detection (LSD) Model*

Image segmentation is a computer vision technique that groups pixels of similar appearance while Line Segment Detection (LSD) models extract line segments from images (Lin et al., 2020; Szeliski, 2022). LSD models extract branch geometry and estimates a straight line representing the branch instead of point clouds and meshes. In our project, we photographed Y-branches on white sheets of paper to reduce environment noise. Photographs were then cropped and resized to 256 x 256 pixels then processed by the LSD model. The model predicted branch features to match the image, but with outer boundary lines rather than center line branch skeletons (Figure 1). Center lines were drawn in Rhino 3D, then piped to match branch diameters.

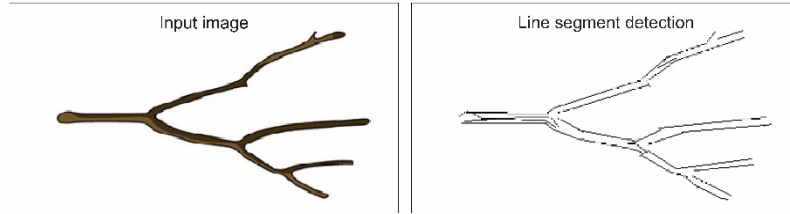


Figure 1. Photo of branch as input (left) and resulting predicted branch features from LSD model (right)

3.1.2. Pix2Pix GAN and Line Segment Detection (LSD) Models

Semantic segmentation models output outer boundaries of objects and cannot detect the central axis lines (Chen et al., 2021). To address this, we developed a Pix2Pix GAN model trained on a custom dataset of 5000 paired synthetic images of branches and their center line skeletons to predict RGB images representative of the branches. To create this synthetic dataset, we used L-systems in Grasshopper 3D to generate rendered branches of varying thickness, materials, and backgrounds in Rhino 3D (Figure 2). To test it, we converted RGB files of 256 x 256 pixels to black and white, then fed them to the Pix2Pix GAN model, and applied the line segment detection (LSD) model to get outer boundaries and vectors. The resulting vector line segments were plotted with the Python library Matplotlib and imported into Rhino 3D with a custom Python plug-in to make the geometry visible. These lines were then scaled up to match the real branch dimensions. The Pix2Pix GAN model was trained on an A100 GPU for 80,000 steps with binary cross entropy and L1 loss.

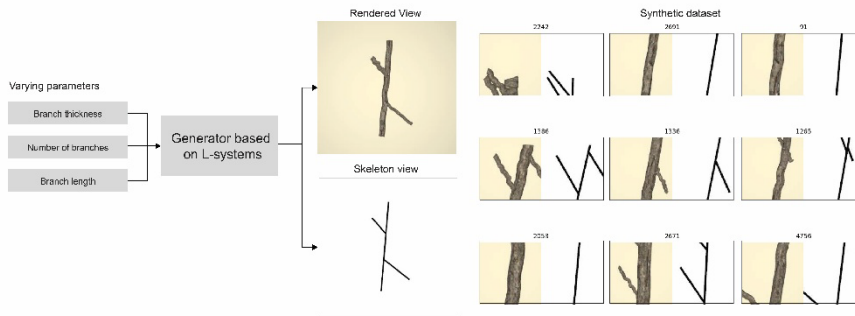


Figure 2. Parameters and synthetic dataset of rendered branches and their center line skeletons used to train Pix2Pix GAN model. This dataset also used to train DDPM model.

3.1.3. Denoising Diffusion Probabilistic Models (DDPM) and LSD

While our Pix2Pix GAN model produced samples closely matching the training images, its performance on real photos did not properly match. To address this, we utilized a Denoising Diffusion Probabilistic Model (DDPM), a machine learning

technique for image generation. DDPMs generate high quality, realistic data from noisy images by reconstructing the data from noise (Ho et al., 2020; Zhao et al., 2025). DDPMs also perform better at data augmentation, thereby improving coverage and robustness. We built the DDPM model with the same synthetic dataset used for the Pix2Pix GAN model. To test it, we fed the DDPM our sized black and white images, plotted resulting vector line segments, and imported them into Rhino 3D (Figure 3). Our model was trained on A100 GPU for 10,000 steps with Mean squared error loss.

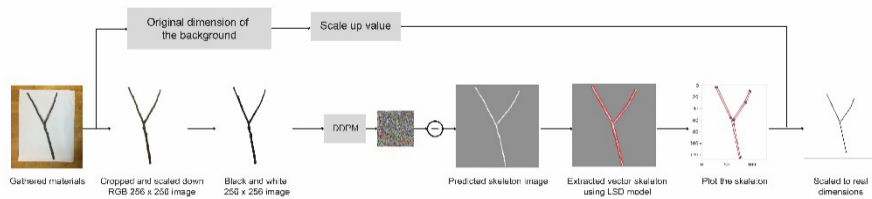


Figure 3. Image of irregular branches from the internet used as input (left), and line segment detection (LSD) model results (right)

3.2. DIGITAL DESIGN WITH IRREGULAR TREE PARTS

We collected Y-branches for the design and fabrication stage after finalizing our DDPM and LSD workflow for extracting geometry from photographs of irregular tree parts. Each branch was labelled before being photographed to improve sorting and recognition in the modeling and design phase (Figure 4).



Figure 4. Collection of labelled Y-branches

3.2.1. Digital Modeling and Sorting of Branches

We imported the vector outputs from our model into Rhino 3D, to digitally model, sort, design, and configure assembly logics and strategies. To digitally model the branches, we piped centerlines to match branch diameters, then labelled each branch in Rhino 3D for identification and assembly. We examined branch characteristics such as slant

angles, height of branch crotch, narrow and wide fork distances, then grouped them based on these metrics. Since our system is currently unable to capture branch depth (Z-axis), we photographed our Y-branches to capture the more complex of the two sides, and privileged branches that did not have large deviations in the Z-axis. This was done to reduce the difference in depth dimension between 2D digital branches and 3D real branches. We designed and fabricated with 2D translations of the 3D branches.

3.2.2. Digital Design with Irregular Branches

We then designed three structures with branches in our digital material library (Figure 5). Structure A comprised eight Y-branches and measured 12" x 12" x 13" (W x L x H) in size. Tall Y-branches would be used for the sides of the arches with Y-branches alternating - one up and one down - while shorter branches rested horizontally across the tall branches. Structure B was dome shaped, comprised 19 Y-branches and measured 14" x 15" x 11". Structure C was trapezoidal-shaped, comprise 14 Y-branches and measured 36" x 48" x 40".

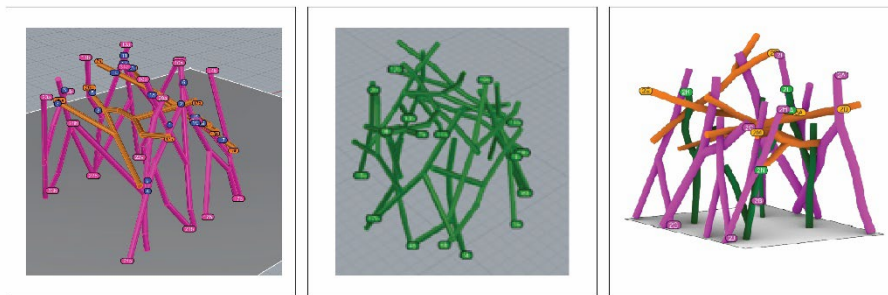


Figure 5. Digital models of designs. Structure A (left), Structure B (middle) and Structure C (right)

3.2.3. Mixed Reality Assembly and Manual Fabrication

The final phase of the workflow involved deploying mixed reality headsets (HoloLens 2) and AR software, Fologram, a plug-in for Grasshopper 3D, to superimpose the digital model from Rhino 3D into the physical workspace, thereby positioning and aligning real tree parts to match the digital model. For structures A and B, branches were secured with hot glue, while for the larger structure, C, we employed square lashing with waxed 9-ply 2mm twine of high tensile strength to rigidly secure the branches. Branch forks and connection points were labelled and marked to differentiate orientation and indicate connection location. Figure 6 shows mixed reality overlays in real space, the square lash, and assembly of the structure by designers wearing HoloLenses.

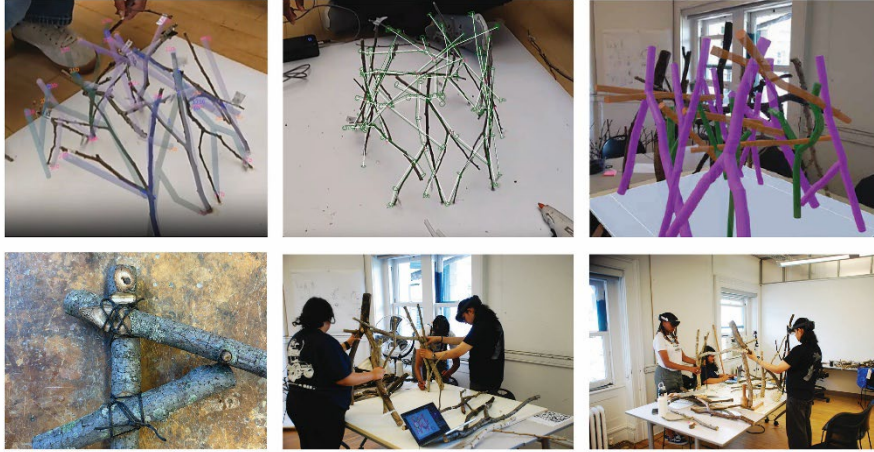


Figure 6. Top row: View through HoloLens showing overlay of digital model onto real space for structures A, B, and C (top left, middle, and right). Bottom row: Square lashing technique (left) and designers fabricating structures with the HoloLens headset on their heads.

4. Results

When it comes to the performance of the machine learning models, GAN achieves an overall accuracy of ~ 0.96 , precision ~ 0.03 , recall ~ 0.16 , F1 score ~ 0.05 , and IoU ~ 0.03 . On the other hand, DDPM achieves ~ 1.00 accuracy, 0.66 precision, 0.76 recall, 0.71 F1, and 0.55 IoU. These scores are shown in Figure 7.

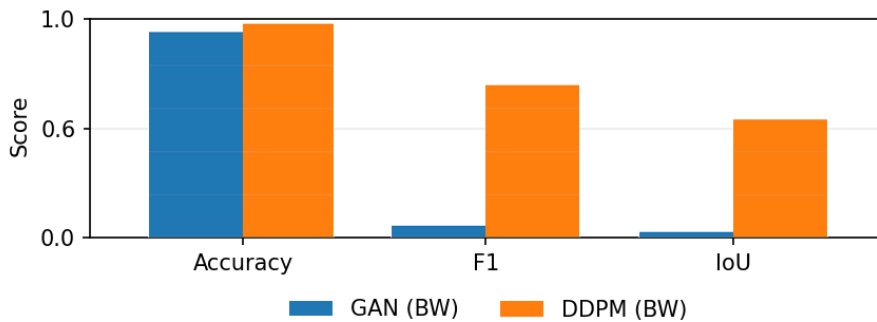


Figure 7. Comparative performance between GAN and DDPM models

Additionally, we present the three structures built with this computational design-to-production workflow comprising Y-branches, computer vision models, digital design and modelling, and augmented reality tools for assembly (Figure 8).



Figure 8. Fabricated structures built with augmented reality (AR) from irregular Y-branches. Structure A (left), structure B (middle) and structure C (right)

5. Discussion and Conclusion

This study aimed to leverage computer vision, digital design and modeling, and augmented reality — to transform otherwise discarded, irregular tree parts into usable building elements. Results show that our Photo2Fab workflow comprising a Denoising Diffusion Probabilistic Model (DDPM) performs better than GAN models in detecting and generalizing skeletons of photos of real tree branches. This project also demonstrates a bottom-up, ecologically responsive approach to material reuse in design, architecture, and construction.

Our finding that DDPM models outperform GAN models, is supported by our experiments and the models' performance, as shown in Figure 7. We evaluated performance based on precision (fraction of correctly predicted 'twig' pixels), recall (fraction of actual 'twig' pixels identified), and the F1-Score (the harmonic mean of precision and recall). In a dataset of approximately 5,000 paired images, we quantitatively compared GAN and DDPM-based predictors using pixel-wise segmentation metrics calibrated for class imbalance. Although the GAN achieves high overall accuracy, precision, recall, F1 score, and IoU, it yields few correct twig pixels. By contrast, DDPM achieves higher scores on all these metrics, reflecting better localization and coverage. These results stress that under severe class imbalance, accuracy is not a reliable diagnostic, and F1 and IoU are more informative, demonstrating better generalization of DDPM to target geometry.

One limitation of this study is that currently the resulting geometry from the model is two-dimensional (2D). This limitation arises from the high computational cost of converting 3D scans into lightweight 3D geometry. This work is still valid, however, since the deviation distance of branches from the mean in the third dimension did not affect design or fabrication at our current scale. Additional directions for future research include developing a ML model that is able to recognize branch depth (Z-axis) so that digital output is 3D, building a Generative Model that can take the geometry of irregular tree parts as input and create three-dimensional digital design options by analyzing and parsing the parts using metrics such as dimensions, shape, and other relevant characteristics.

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